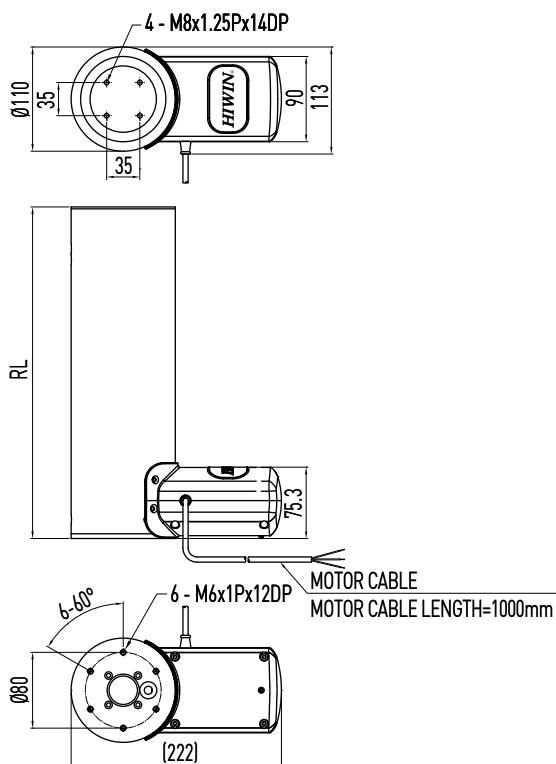


# Linear Actuator

## LAC Series

### 20. HIWIN LAC Series (1)

#### LAC1



- $RL = 150 + S/2$   
 RL: Retracted length  
 S: Stroke length

Table 20.1 Specifications

Screw type	ACME
Weight*	5.6kg
Protection	IP54
Compatible controller	Compatible with all controllers (*Notice the type of connector: Audio/DIN 4pin)
Working temp.	+5°C~40°C

\* Stroke length 400mm

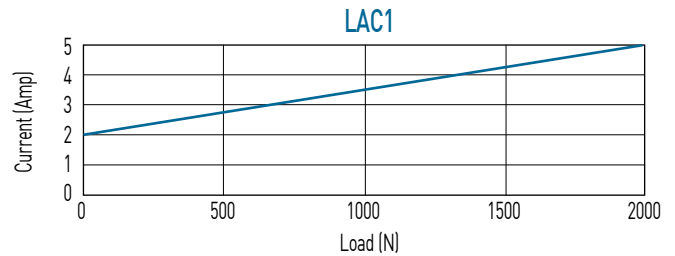
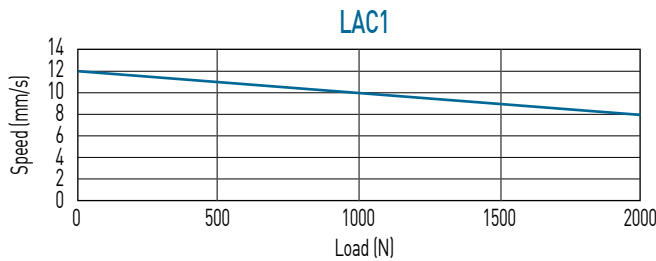
#### Option:

- (1) Hall sensor
- (2) Potentiometer
- (3) Plug : DIN 4PIN plug / Stereo plug / Mono plug

Table 20.2 LAC1 Specifications

Model	Thrust max. (N)	Pulling max. (N)	Holding max. (N)	Speed (mm / s) Load = Max. / Load = 0	Standard stroke (mm) : S	Duty cycle %	Current max. (A) 24VDC	Potentiometer Resolution (ohm/mm)	Hall Sensor Resolution (mm/pulse)
LAC1-1	2000	500	2000	8 / 12	300 400 500	10	5	6.67	0.064

\* Min. input power = Voltage x Current max.

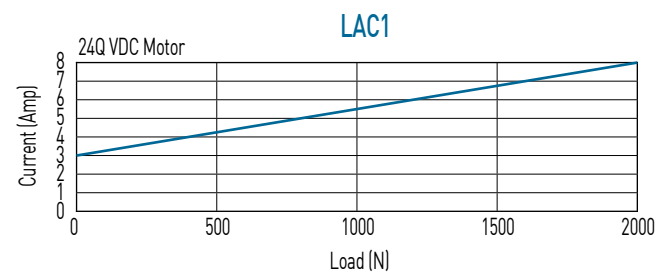
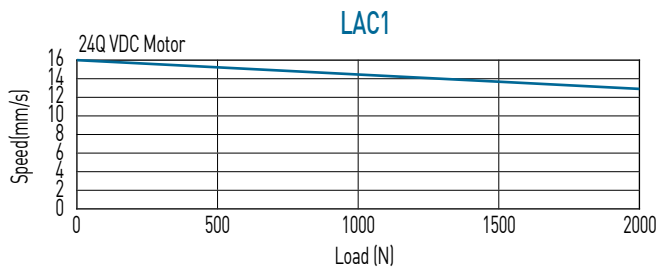


\*\*Note: The test results are obtained by using the 24VDC power supply.

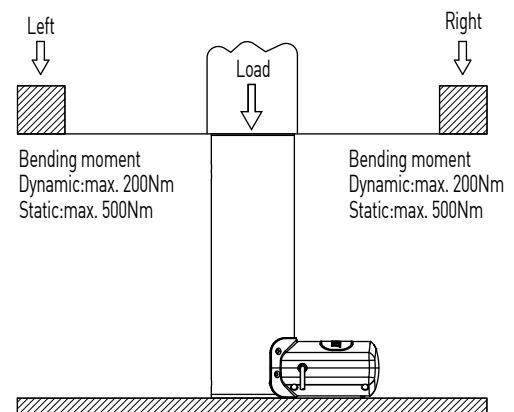
Table 20.3 LAC1(24Q) Specifications

Model	Thrust max. (N)	Pulling max. (N)	Holding max. (N)	Speed (mm / s) Load = Max. / Load = 0	Standard stroke (mm) : S	Duty cycle %	Current max. (A) 24VDC	Potentiometer Resolution (ohm/mm)	Hall Sensor Resolution (mm/pulse)
LAC1-1	2000	500	2000	13/16	300 400 500	10	8	6.67	0.064

\* Min. input power = Voltage x Current max.



### LAC1 Bending moment illustration



### Ordering Information

